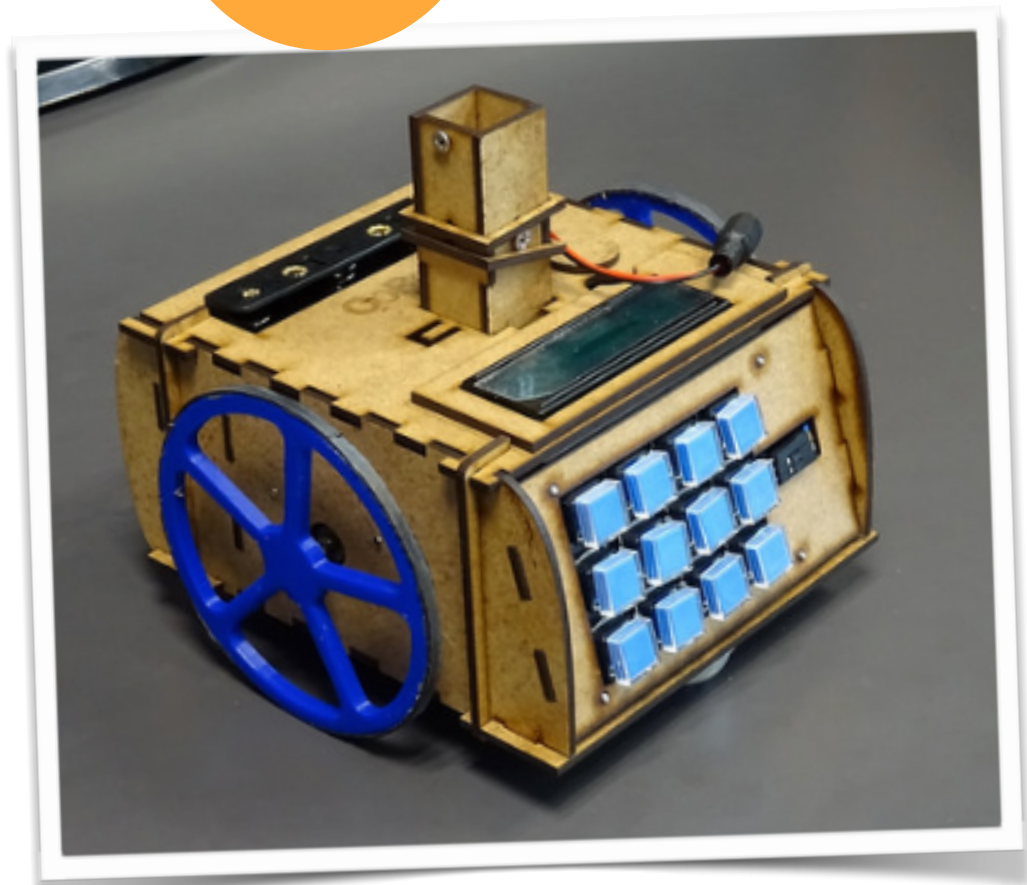


Notice de montage Oo-RoBot pour

Cycle  
3

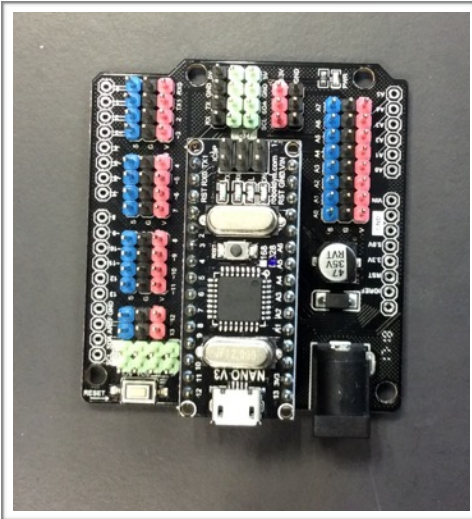
**BETA**



d'après un projet développé par Matthieu Salvat  
document élaboré par Jérôme Breheret et gilles tisseraud

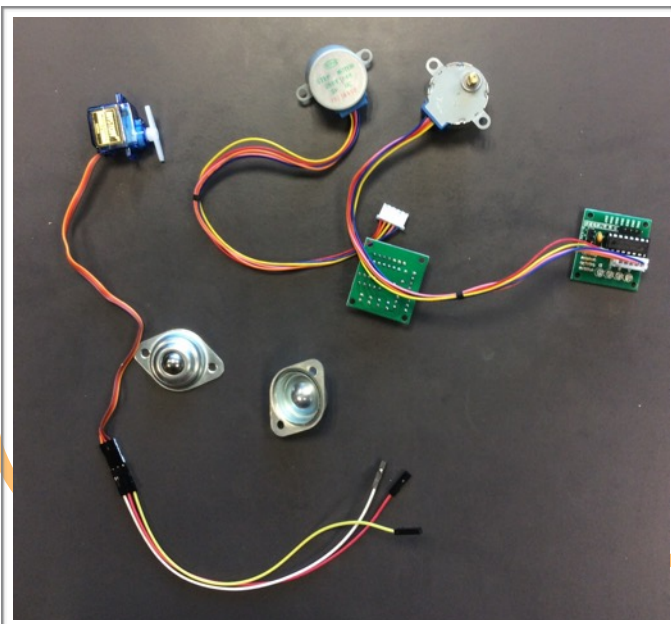
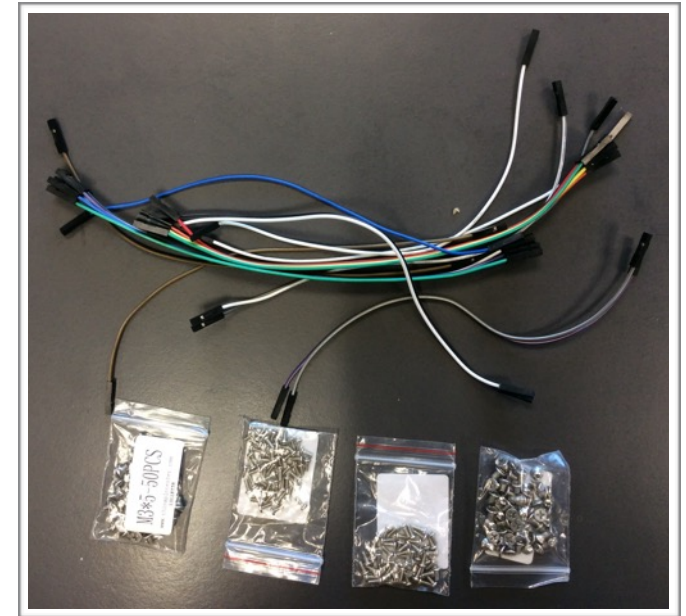
I

*Je vérifie et j'organise mon matériel en les regroupant*



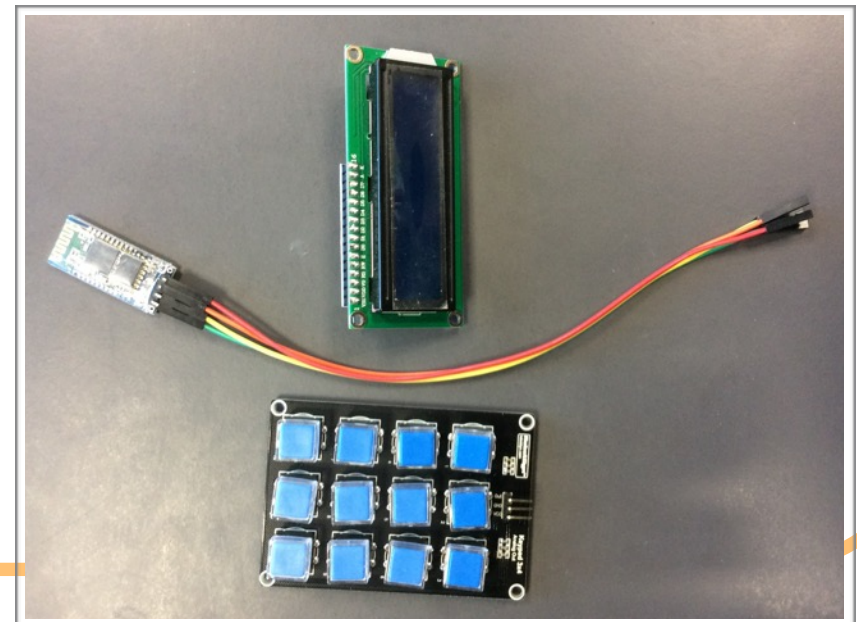
*la carte mère  
(centre de mon robot)*

*les connecteurs et la visserie*



*les moteurs*

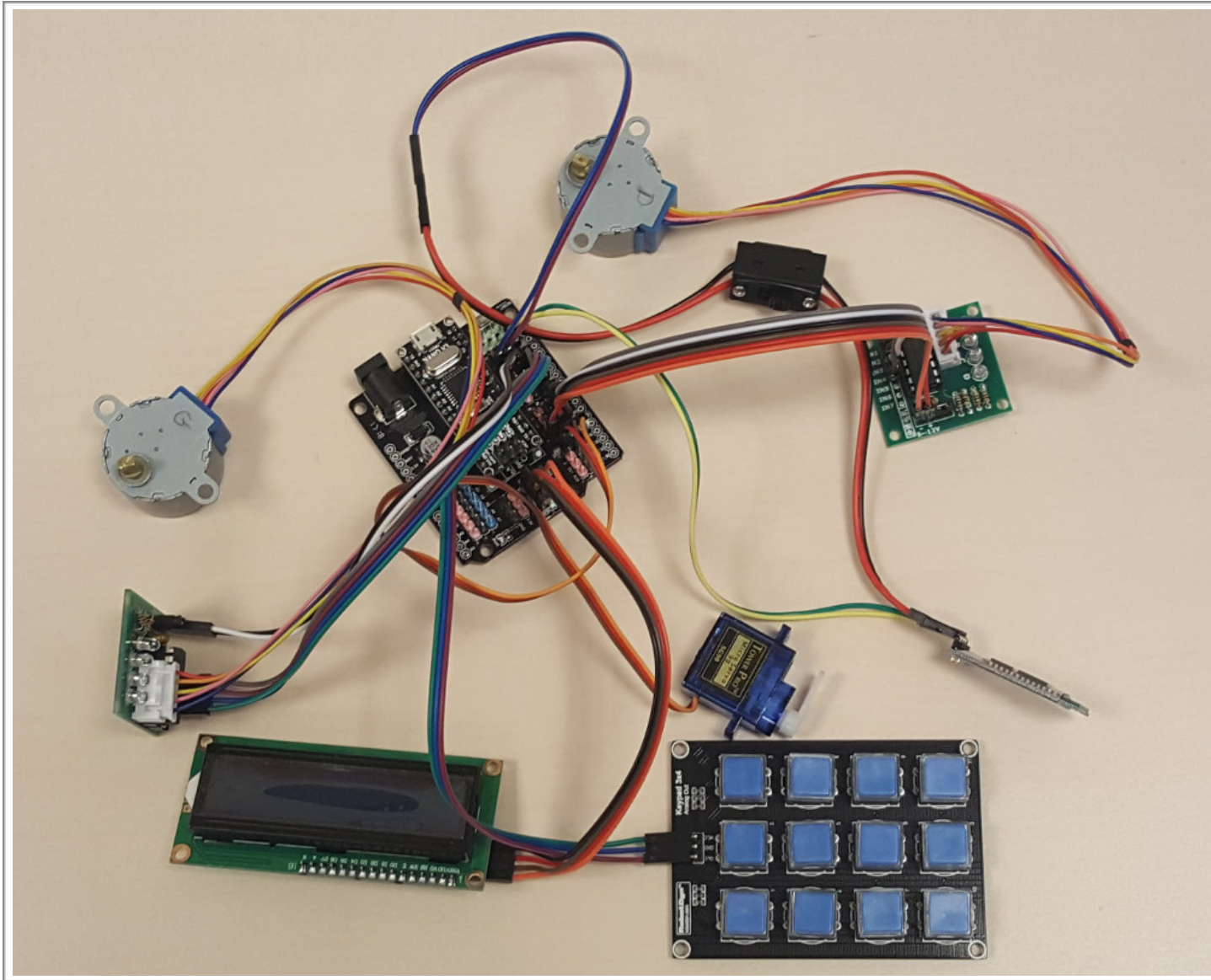
*le panneau de  
commandes*





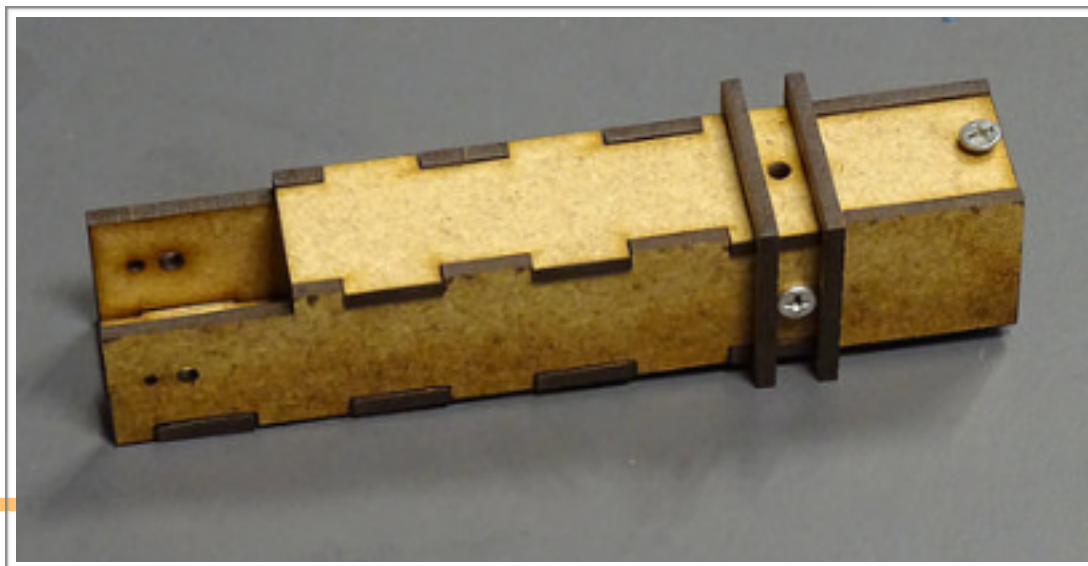
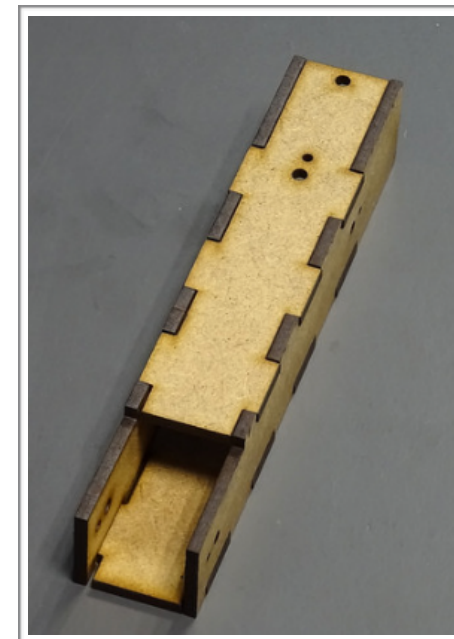
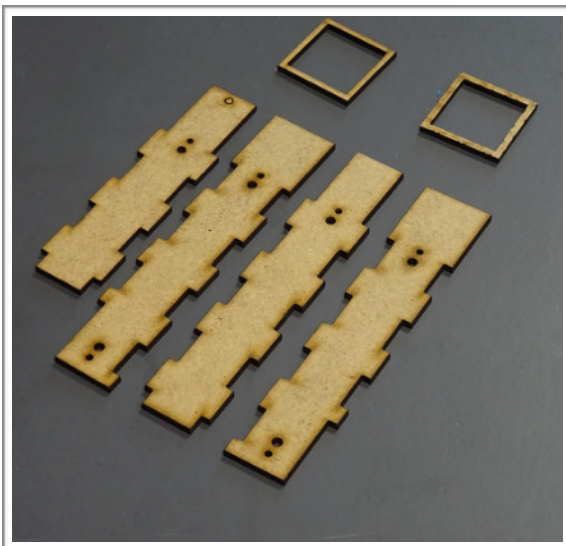
2

*Aperçu du montage électronique final.*



3

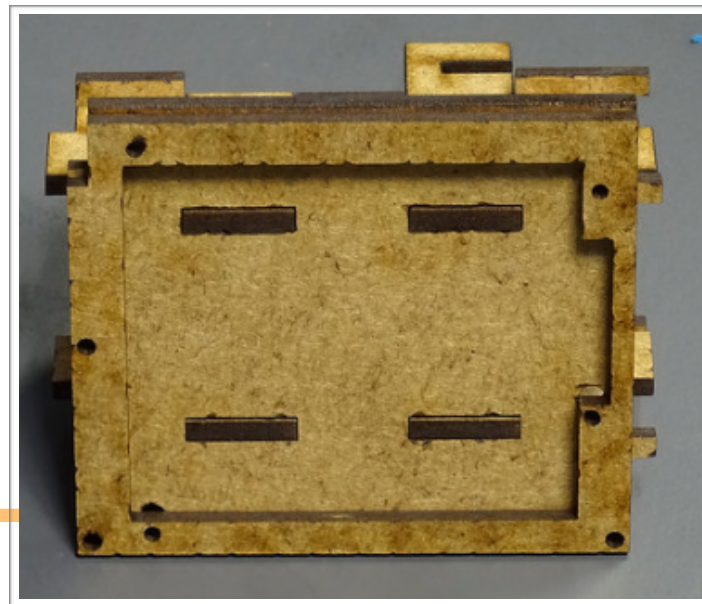
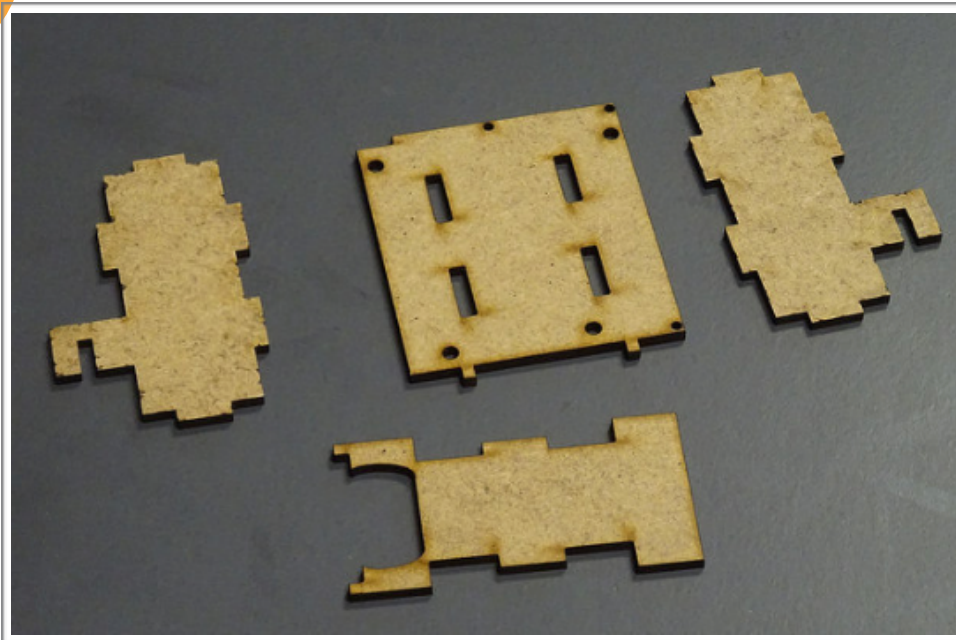
*C'est parti ! Tout d'abord, on assemble la lère partie du support à crayon*





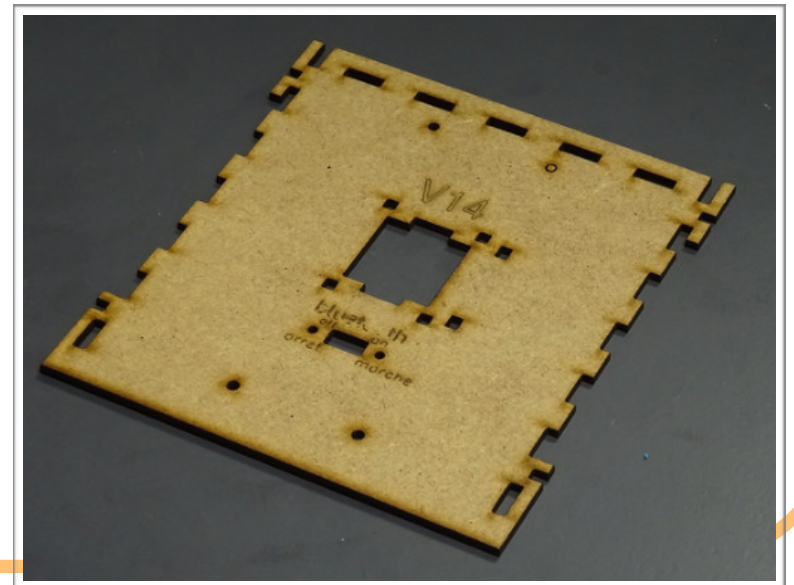
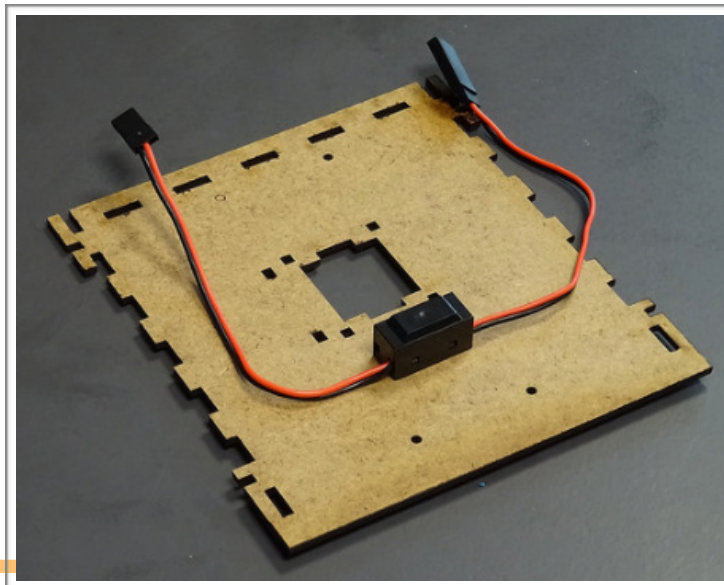
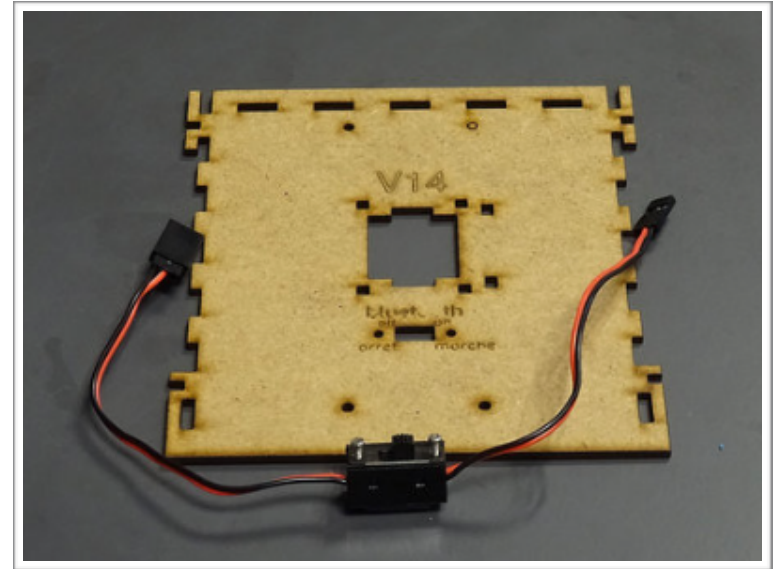
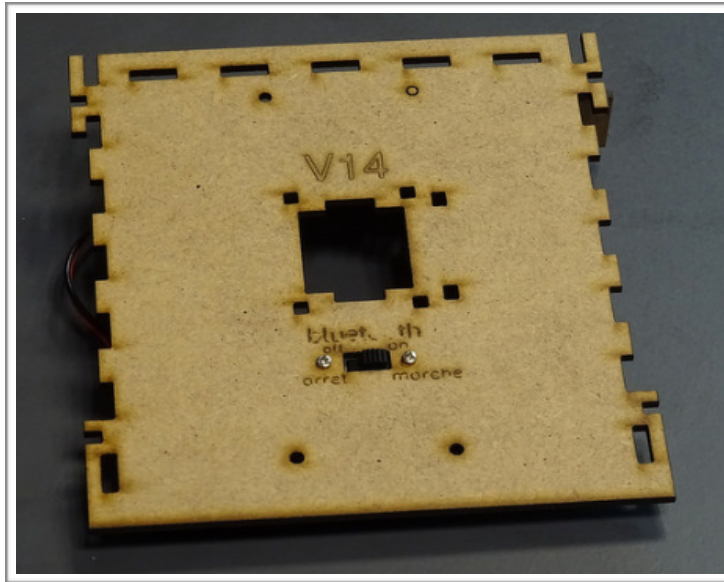
4

*Maintenant on assemble la partie externe du support à crayon*



5

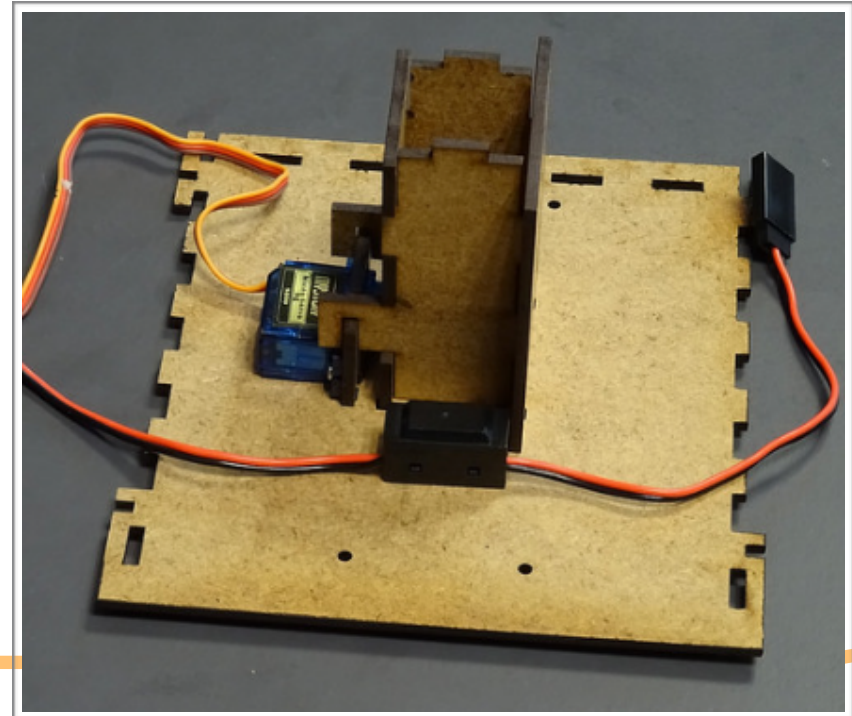
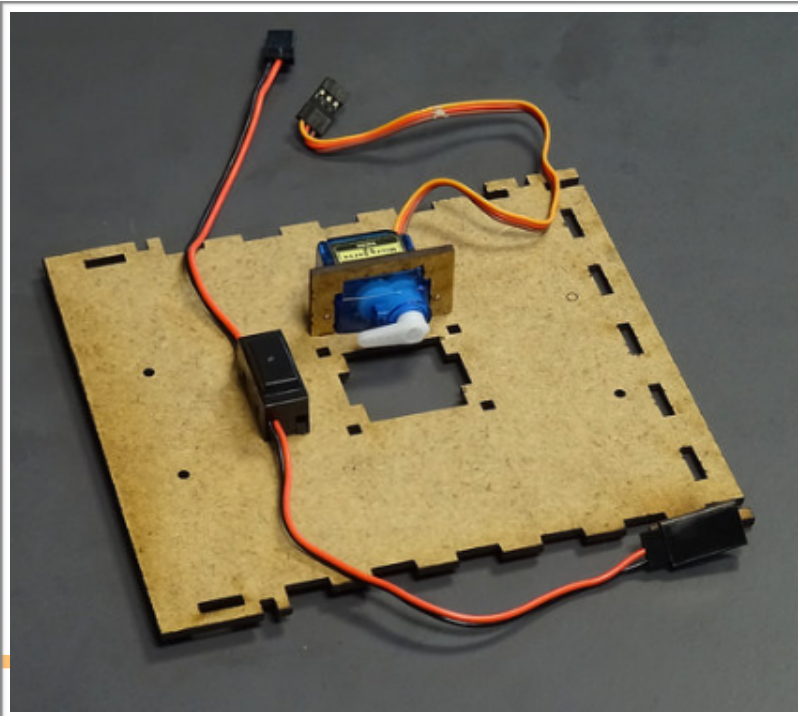
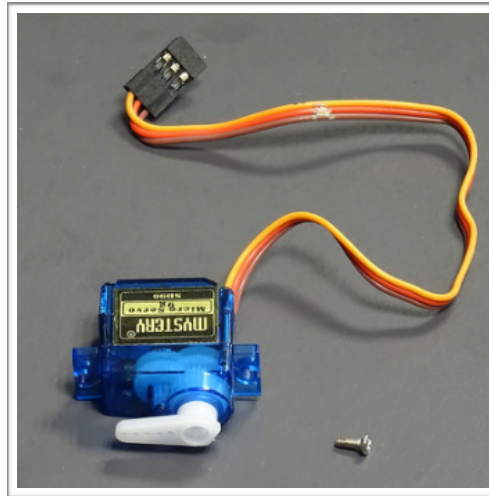
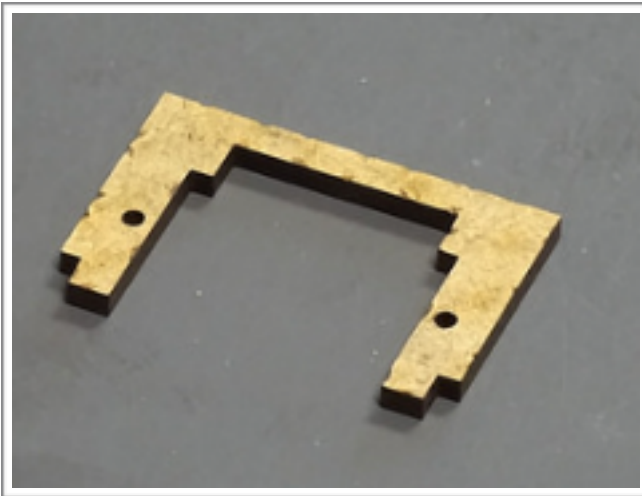
*On attaque l'assemblage du corps en commençant par fixer l'interrupteur*





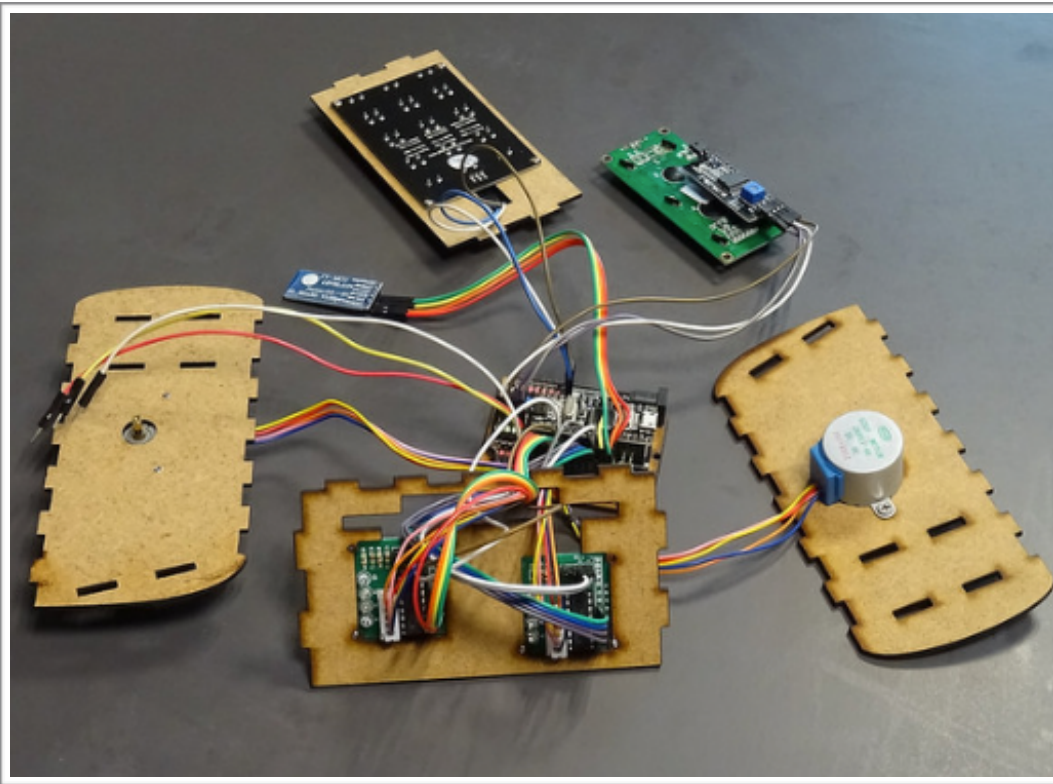
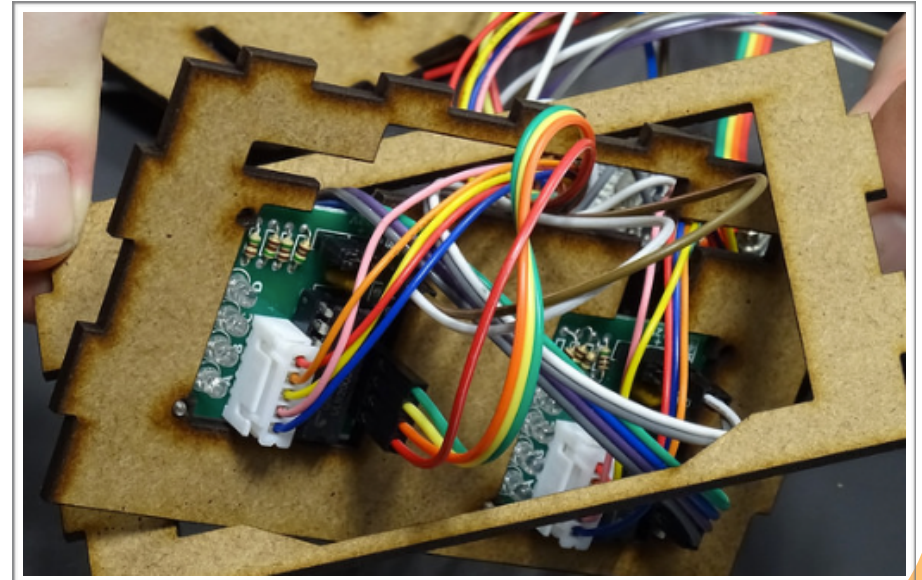
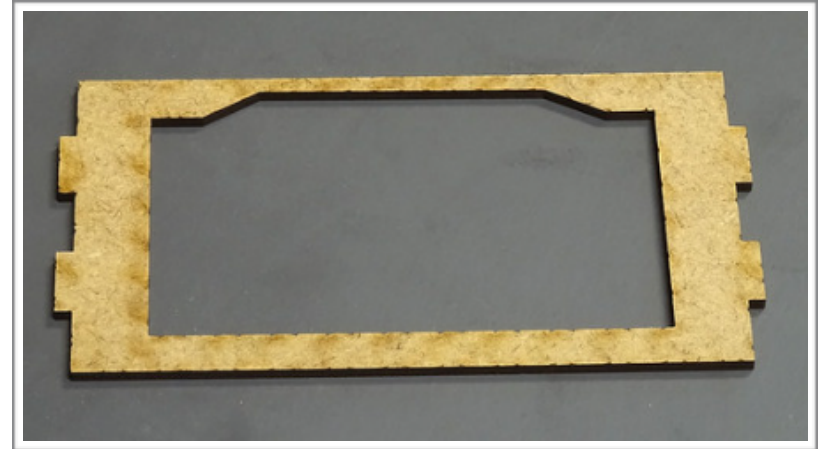
6

*Et si on s'occupait des servo moteurs ?*



7

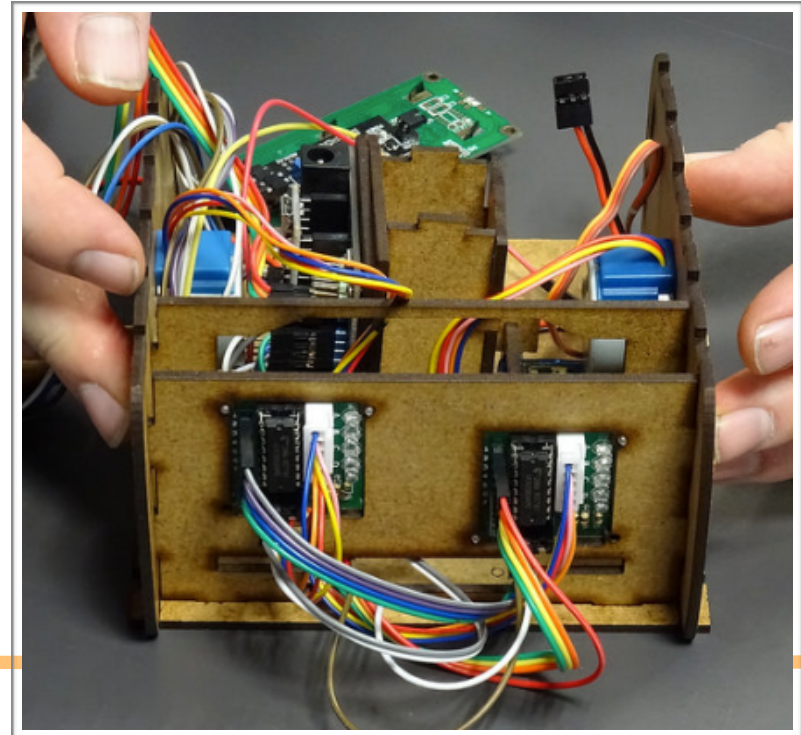
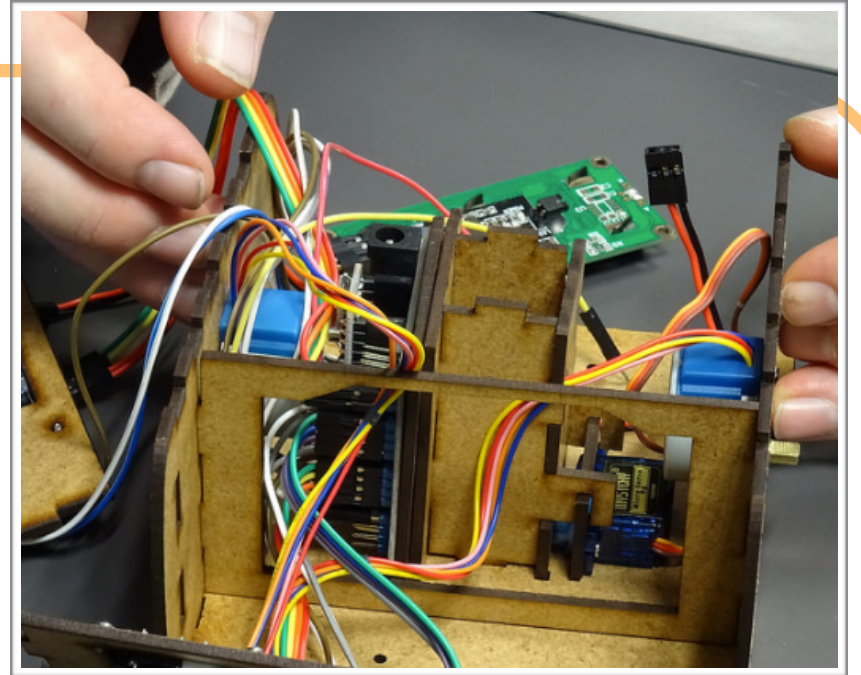
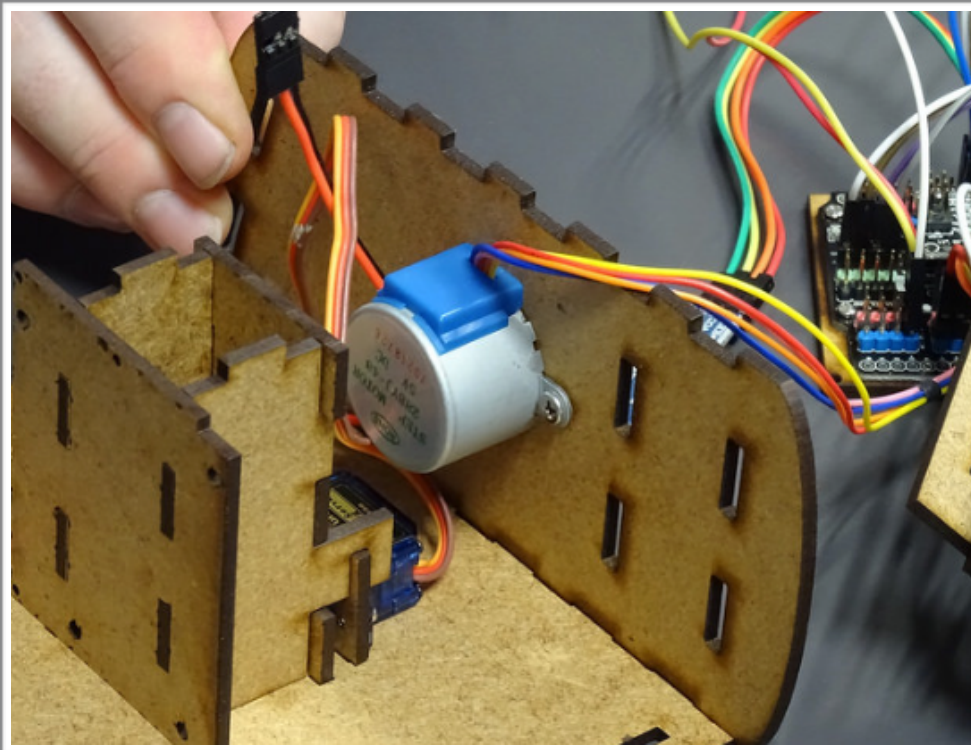
*Attention pour cette étape, soyez particulièrement vigilants à l'assemblage et aux branchements.*





8

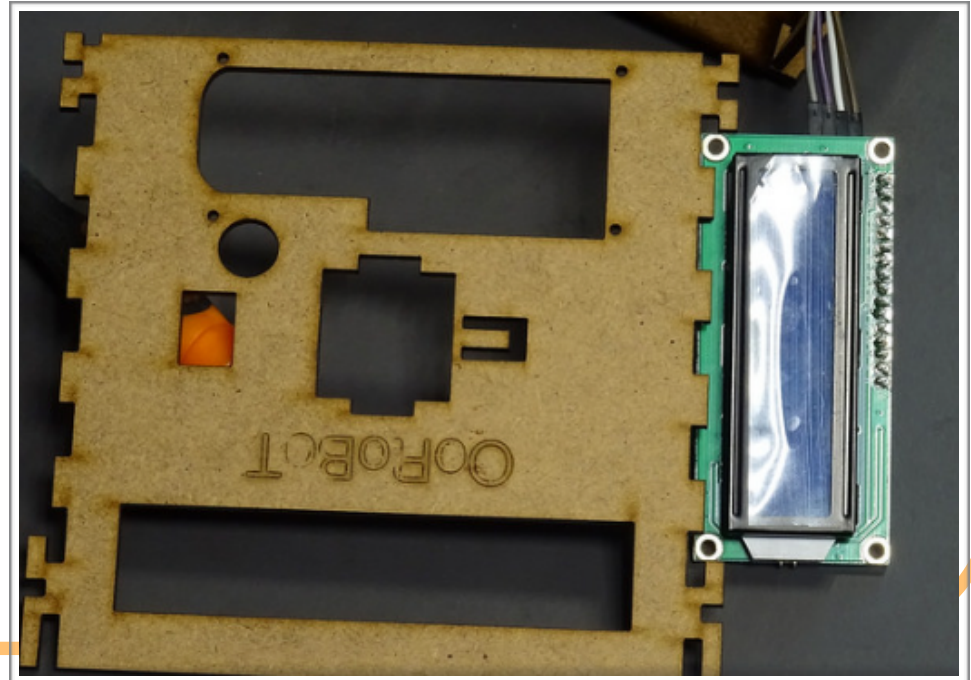
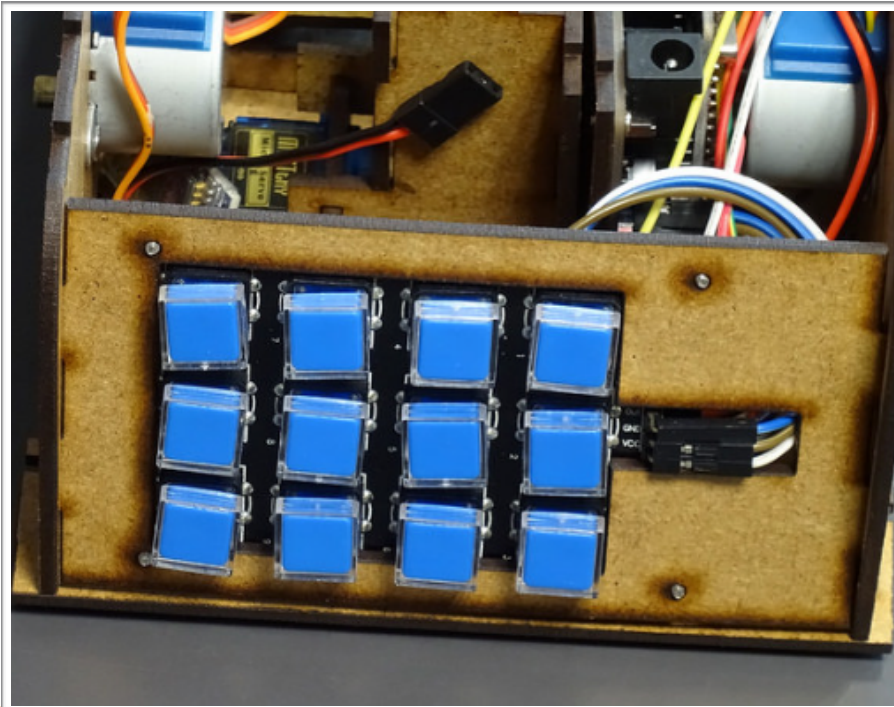
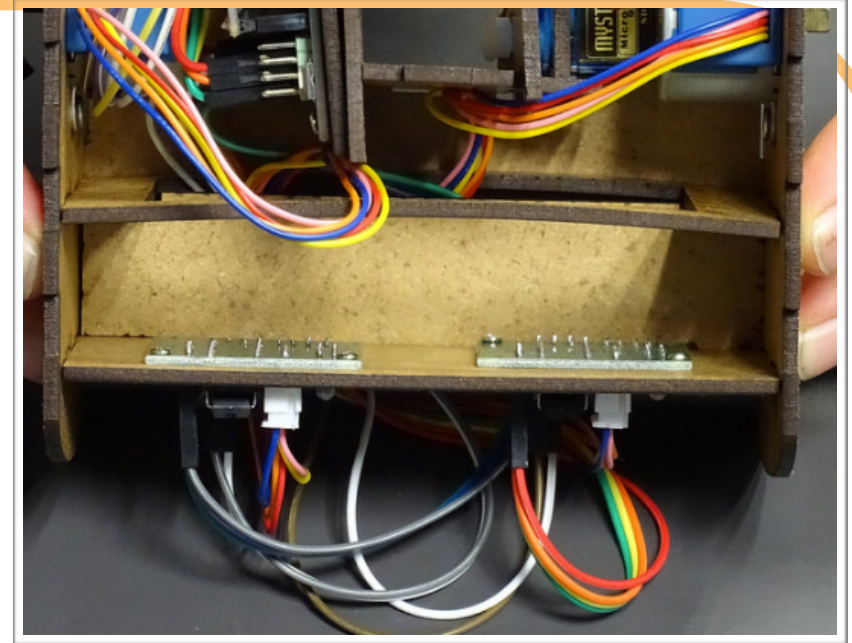
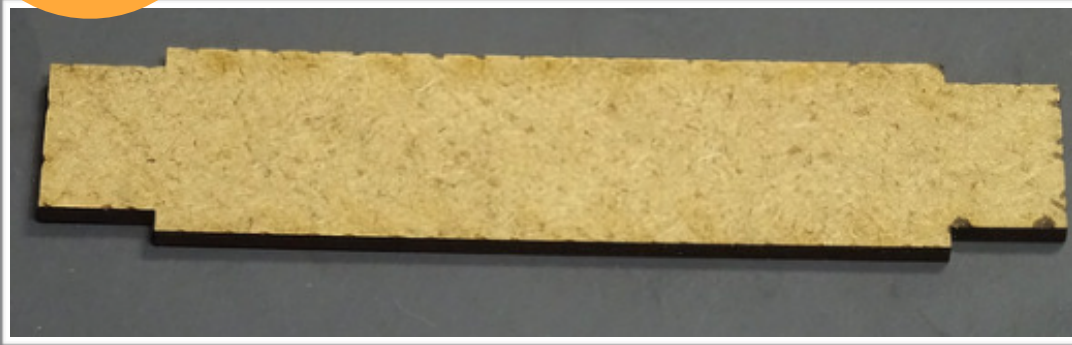
*Suite de l'étape....*





9

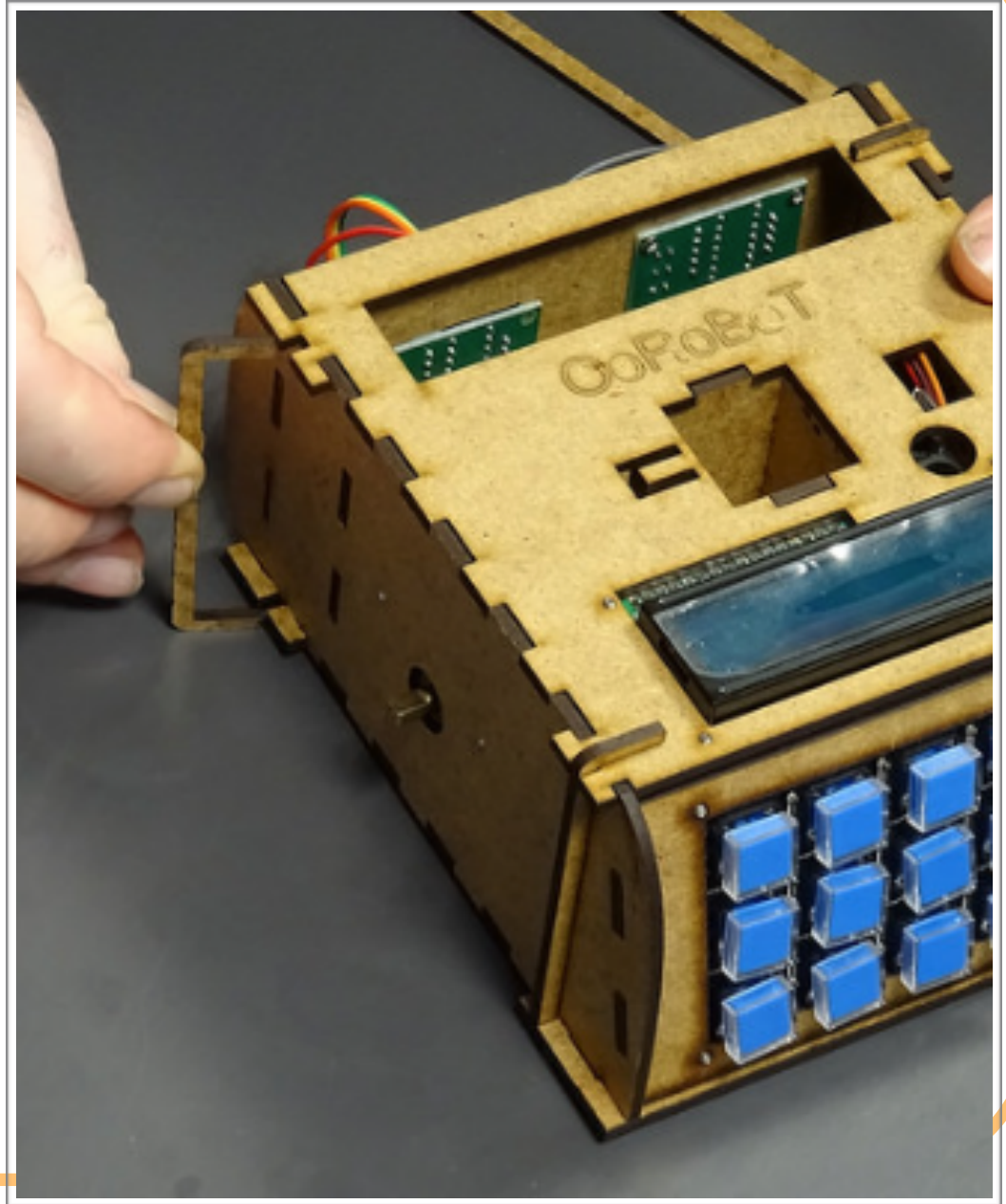
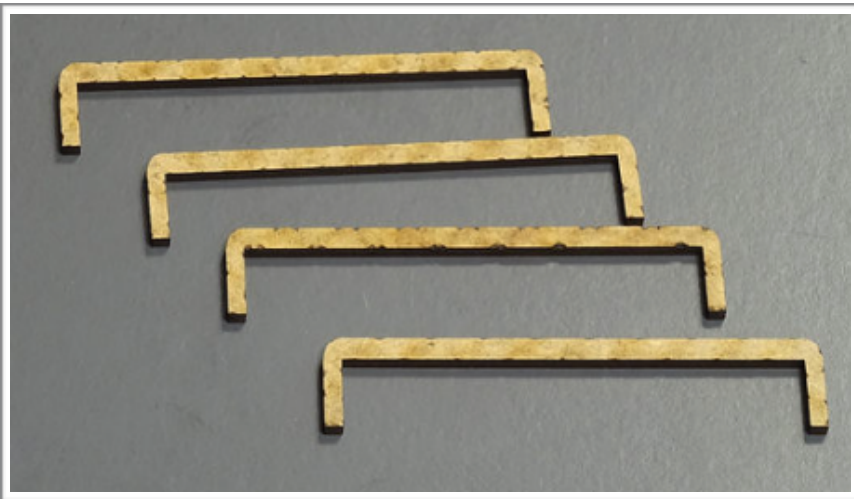
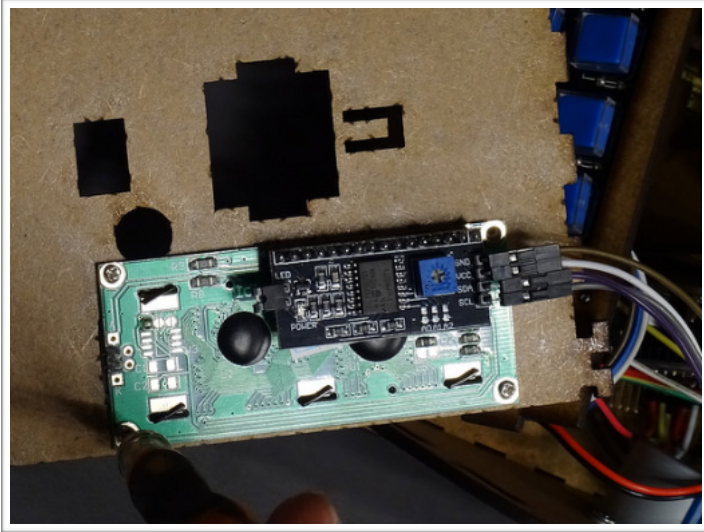
*Allez, courage, on continue l'assemblage!*





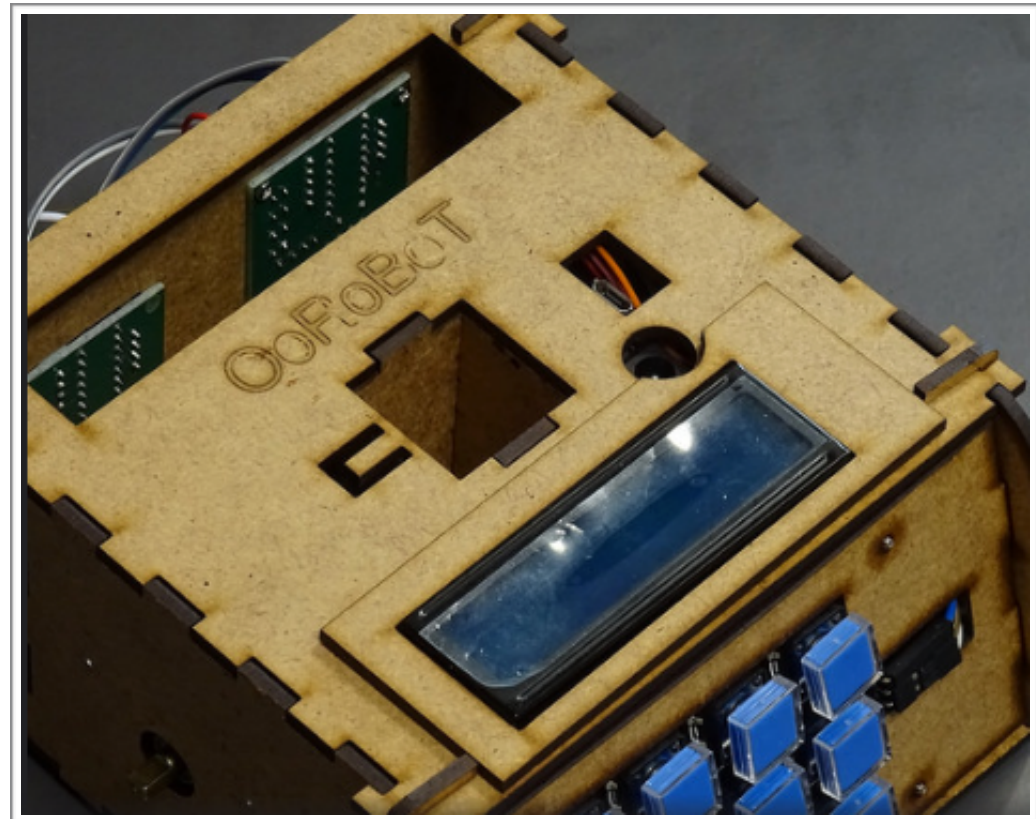
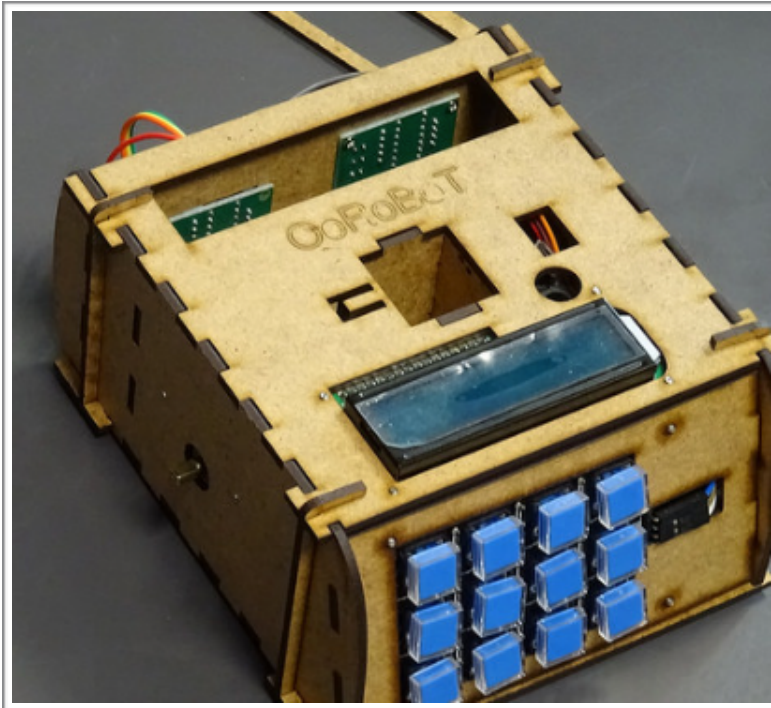
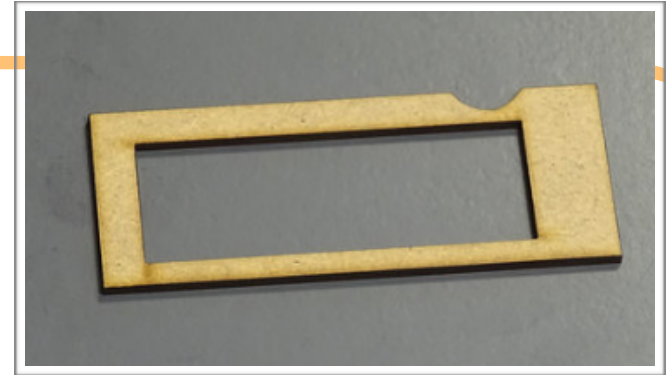
10

Fixation des ergots en « U »





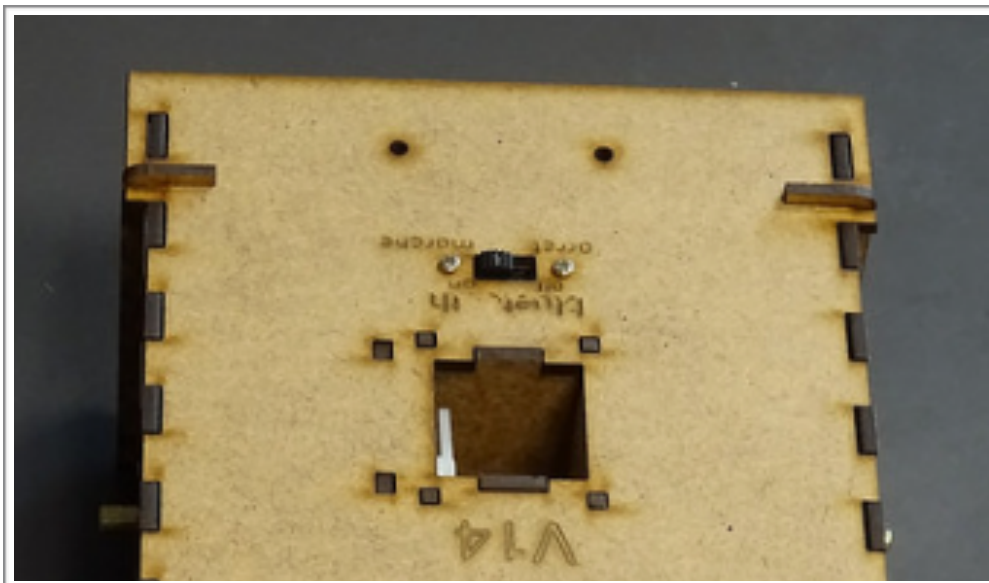
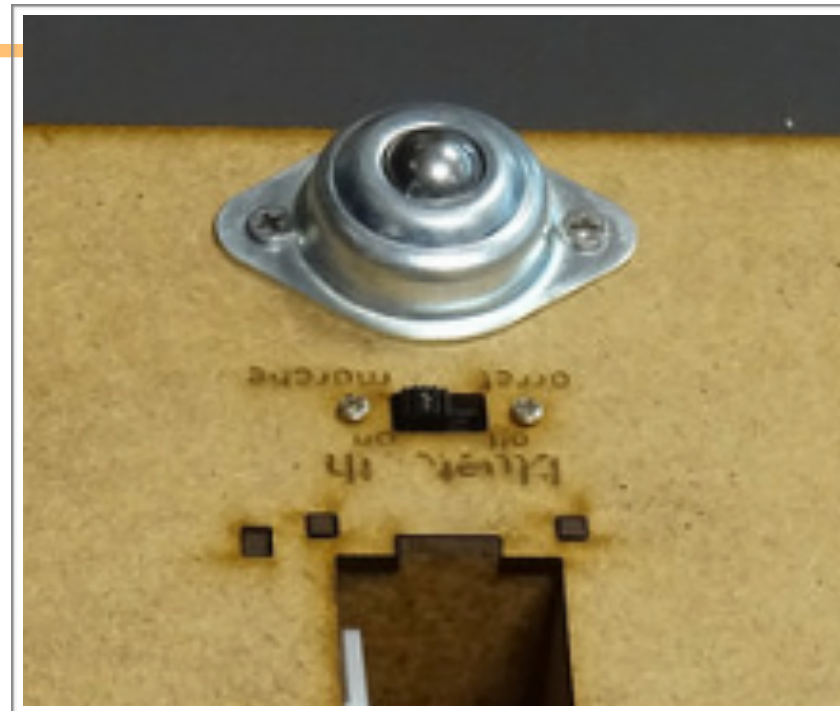
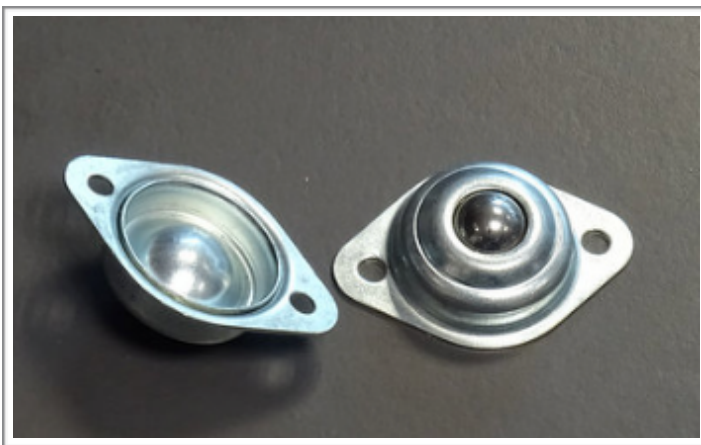
*il est temps de coller le cache écran à cristaux liquides*





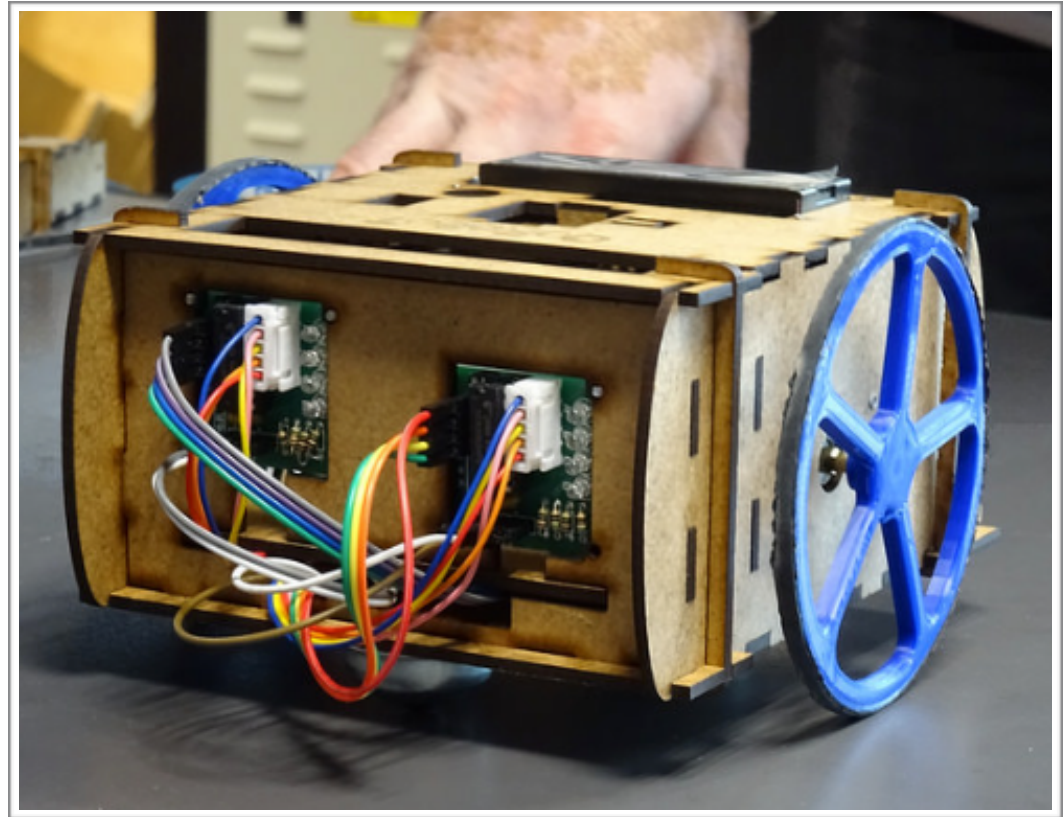
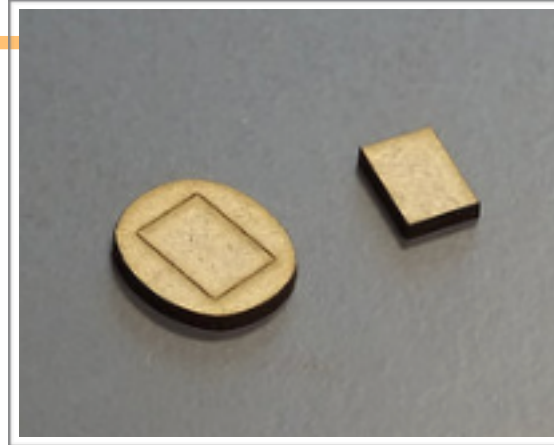
12

*On place la roue pivot sous le robot*



13

*La dernière étape...*





14

*Et voilà, le robot est maintenant  
achevé ! Bravo !*

